

# **Algorithms and Complexity**

## Lecture 7

Dynamic Programming and  
Inclusion Exclusion

# Overview of Today

- Dynamic Programming
  - Subset Sum / Knapsack approximation
  - Coloring
  - Traveling Salesman Problem
  - Steiner Tree
  - Weighted Independent Set on trees
- Inclusion Exclusion
  - Hamiltonian Cycle
  - k-coloring

# Dynamic Programming (DP)

- The method works with a big table of data that has to be stored in memory.
- A relatively easy procedure computes new table entries using already computed table entries.
- This easy procedure is often so easy that we just write it down as a single formula, obtaining a *recurrence*.
- Other interpretation:
  - cleverly define subproblems,
  - solve easier subproblems first; store solutions
  - use solutions of easier subproblem to solve harder ones
  - the original problem also is a subproblem

# Subset Sum

- Given integers  $w_1, \dots, w_n, t$  find  $X \subseteq \{1, \dots, n\}$  such that  $\sum_{i \in X} w_i = t$ .
- For  $i = 1, \dots, n$  and  $j = 1, \dots, t$  define  $A[i, j]$  to be true iff  $\exists X \subseteq \{1, \dots, i\}$  s.t.  $\sum_{i \in X} w_i = j$ . Want:  $A[n, t]$
- Instance  $\{1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12\}$ ,  $t = 50$
- True/false:  $A[0,0], A[2,0], A[3,5], A[6,12], A[4,20], A[12,50]$ ?

$$A[i, j] = \begin{cases} \text{false} & \text{if } i = 0, j > 0, \\ \text{true} & \text{if } i = 0, j = 0, \\ A[i - 1, j] & \text{if } i > 0, j < w_i, \\ A[i - 1, j] \vee A[i - 1, j - w_i] & \text{otherwise.} \end{cases}$$

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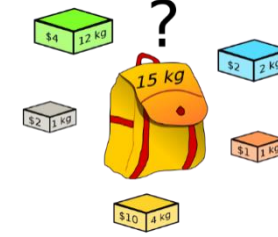
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- $O(nt)$  time
- Not polynomial:  $t$  can be exponentially large since it is represented in binary!

# Knapsack



- Given  $w_1, \dots, w_n, b, v_1, \dots, v_n, t$ ,  
find  $X \subseteq \{1, \dots, n\}$  s.t.  $\sum_{e \in X} v_e \geq t, \sum_{e \in X} w_e \leq b$ .

- For  $i = 0, \dots, n$  and  $j = 0, \dots, V := \sum_e v_e$  let

$$A[i, j] = \min\{\sum_{e \in X} w_e : X \subseteq \{1, \dots, i\} \wedge \sum_{e \in X} v_e \geq j\}$$

- $A[i, j]$  is minimum weight of a subset realizing a given value

$$A[i, j] = \begin{cases} 0 & \text{if } i = 0, j \leq 0, \\ \infty & \text{if } i = 0, j > 0, \\ \min\{A[i - 1, j], A[i - 1, \max\{j - v_i, 0\}]\} & \text{if } i > 0. \end{cases}$$

- Can *find* in  $O(nV)$  time set  $X$  maximizing

$$\sum_{e \in X} v_e \text{ s.t. } \sum_{e \in X} w_e \leq b:$$

- Let  $v$  be largest value s.t.  $T[n, v] \leq b$
- Backtrack from  $T[n, v]$  (Exercise 6.1)



# Approximation scheme for Knapsack

- This DP is again pseudopolynomial
- We'll see a  $O(n^3/\epsilon)$  time  $(1 - \epsilon)$ -approximation for the maximization version of knapsack
- I.e., find in time  $O(n^3/\epsilon)$  a set  $A$  such that:
  - $\sum_{i \in A} w_i \leq b$ , and
  - for every  $X$  satisfying  $\sum_{i \in X} w_i \leq b$ 
    - $\sum_{i \in A} v_i \geq (1 - \epsilon) \sum_{i \in X} v_i$

# Approximation scheme for Knapsack

- Idea:
  1. Can replace instance  $w_1, \dots, w_n, b, v_1 \cdot S, \dots, v_n \cdot S$ , with  $w_1, \dots, w_n, b, v_1, \dots, v_n$ 
    - Optimum stays the same! Useful if  $S$  large!
  2. Round values to multiples of  $S$

# Approximation for Knapsack

- L4 runs in time

$$O\left(n \sum_i \frac{\tilde{v}_i}{S}\right) = O\left(n \sum_i \frac{v_i}{S}\right) = O\left(n^2 \left(\frac{v_{\max}}{S}\right)\right) = O\left(\frac{n^3}{\epsilon}\right)$$

- Output  $A$  satisfies  $\sum_{e \in A} w_e \leq b$
- It remains to compare  $A$  with  $X$  that reaches  $OPT$

**Algorithm** `apxKnapsack`( $w_1, \dots, w_n, v_1, \dots, v_n, b, \epsilon$ )

assumes  $\max_i w_i \leq b$

**Output:**  $A$  s.t.  $\sum_{e \in A} w_e \leq b \wedge \sum_{e \in A} v_e \geq (1 - \epsilon)OPT$

$OPT = \max\{\sum_{e \in X} v_e : \sum_{e \in X} w_e \leq b\}$

1: let  $v_{\max} = \max_i v_i$ , let  $S = \lfloor \frac{\epsilon v_{\max}}{n} \rfloor$

2: **for all**  $i = 1, \dots, n$  **do**

3:  $\tilde{v}_i = S \lfloor \frac{v_i}{S} \rfloor$

4: **return** `optKnapsack`( $w_1, \dots, w_n, \tilde{v}_1/S, \dots, \tilde{v}_n/S, b$ )

# Approximation for Knapsack

- Suppose that  $X$  is optimal solution (value is  $\sum_{i \in X} v_i$ )
- In rounded instance, value of  $X$  is
$$\sum_{i \in X} S \lfloor v_i/S \rfloor \geq \sum_{i \in X} v_i - S$$
- Thus, loss is at most  $nS \leq n \frac{\epsilon \cdot v_{max}}{n} \leq \epsilon \cdot v_{max} \leq \epsilon \cdot OPT$   
( $OPT \geq v_{max}$ )
- Value of rounded instance is  $\geq OPT - \epsilon \cdot OPT$

**Algorithm** `apxKnapsack`( $w_1, \dots, w_n, v_1, \dots, v_n, b, \epsilon$ )

assumes  $\max_i w_i \leq b$

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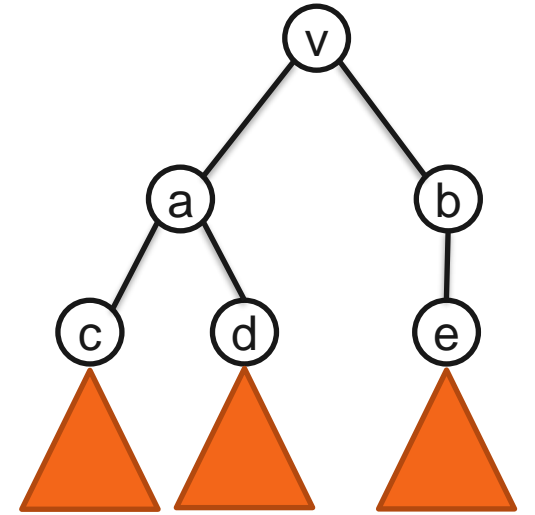
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# Weighted Independent Set in Trees

- Many NP-hard problem are easy on trees
- In weighted independent set the vertices have weights and we want to find a max. weight ind. set.
- Let  $T$  be a rooted tree,  $T[v]$  the subtree rooted at  $v \in V$ . Define  $A[v]$  as the max weight of an ind. set of  $T[v]$ , then

$$A[v] = \begin{cases} \omega(v), & \text{if } T[v] \text{ is a single node,} \\ \max \left\{ \sum_{c \in \text{ch}(v)} A[c], \omega(v) + \sum_{c_1 \in \text{ch}(v)} \sum_{c_2 \in \text{ch}(c_1)} A[c_2] \right\}, & \text{otherwise.} \end{cases}$$

- And we can compute  $A[\text{root}]$  in  $O(n)$  time.

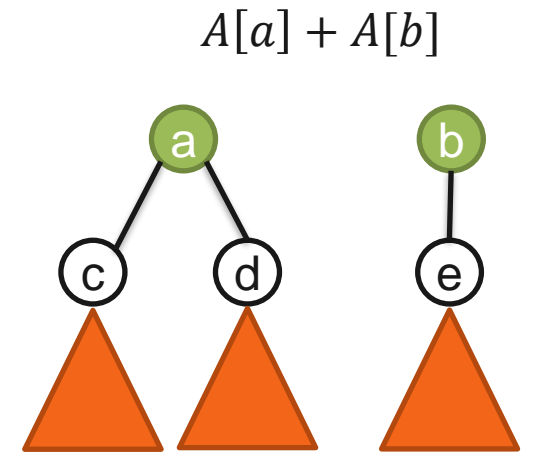


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$$A[v] = \begin{cases} \omega(v), & \text{if } T[v] \text{ is a single node,} \\ \max \left\{ \sum_{c \in \text{ch}(v)} A[c], \omega(v) + \sum_{c_1 \in \text{ch}(v)} \sum_{c_2 \in \text{ch}(c_1)} A[c_2] \right\}, & \text{otherwise.} \end{cases}$$

- And we can compute  $A[\text{root}]$  in  $O(n)$  time.

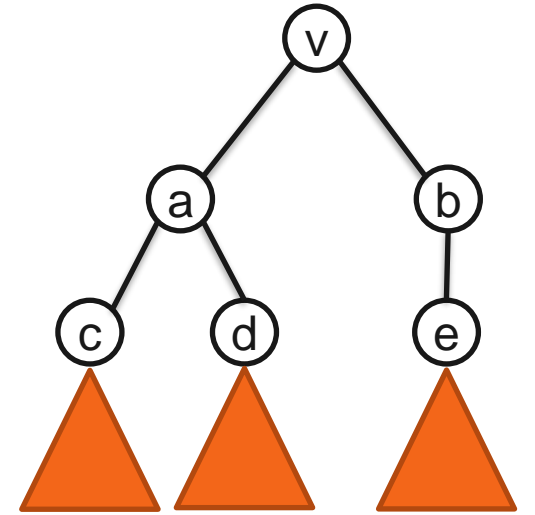


# Weighted Independent Set in Trees

- Many NP-hard problem are easy on trees
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# Weighted Independent Set in Trees

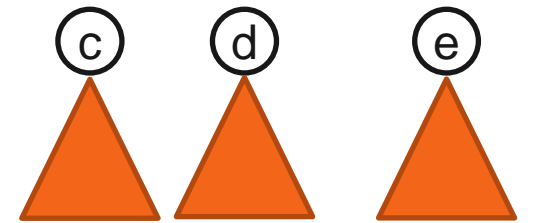
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$$\omega(v) + A[c] + A[d] + A[e]$$





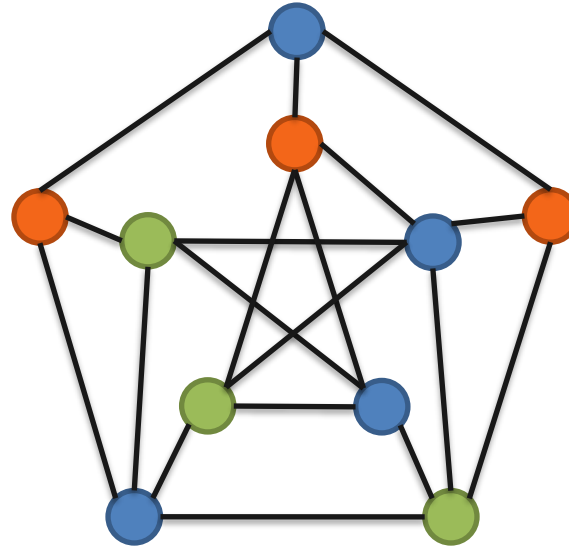
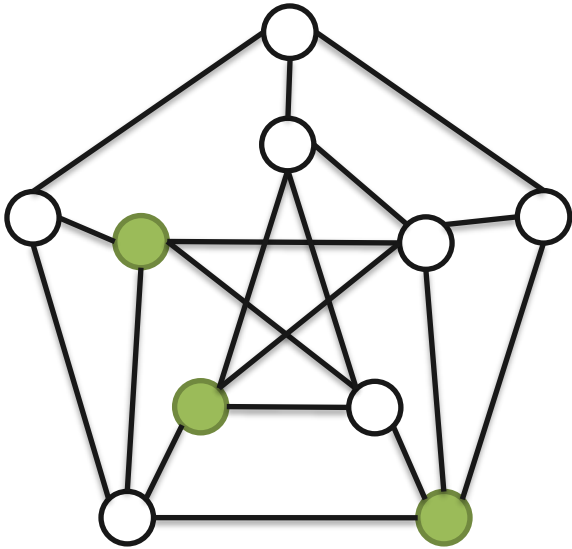
# k-coloring in $O^*(3^n)$

- Previous lecture: saw brute force for 3-coloring in  $O^*(3^n)$  time; improved to  $O^*(2^n)$  time using smarter branching
- Now:  $k$ -coloring for arbitrary  $k$  in  $O^*(3^n)$

# k-coloring in $O^*(3^n)$

- Define  $A_k[X] = [G[X] \text{ is } k\text{-colorable}]$

$$A_k[X] = \begin{cases} \text{true,} & \text{if } k = 1, X \text{ is an independent set of } G \\ \text{false,} & \text{if } k = 1, X \text{ is not an independent set of } G \\ \bigvee_{Y \subseteq X} A_{k-1}[X \setminus Y] \wedge A_1[Y], & \text{otherwise.} \end{cases}$$



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**Algorithm** kcolor( $G = (V, E), k$ )

**Output:** Whether  $G$  is  $k$ -colorable.

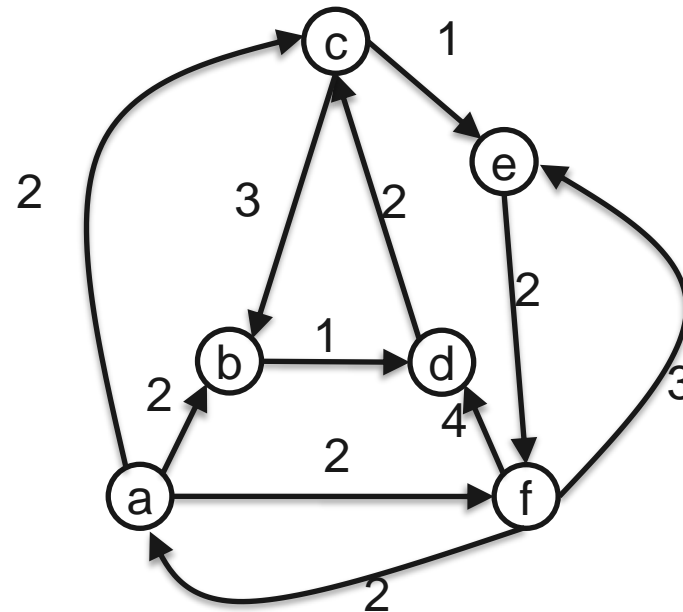
```
1: for  $X \subseteq V$  do
2:   if  $X$  is an independent set of  $G$  then set  $A_1[X] = \text{true}$  else set  $A_1[X] = \text{false}$ 
3: for  $l = 2$  to  $k$  do
4:   for  $X \subseteq V$  do
5:     set  $A_l[X] = \text{false}$ 
6:     for  $Y \subseteq X$  do
7:       if  $A_{l-1}[X \setminus Y] \wedge A_1[Y]$  then set  $A_l[X] = \text{true}$ 
8: return  $A_k[V]$ 
```

$$(x + y)^n = \sum_{k=0}^n \binom{n}{k} x^k y^{n-k}$$

- $\text{poly}(n) \sum_{i=1}^n \binom{n}{i} 2^i = O^*(3^n)$  time by bin. thm.

# Traveling Salesman Problem

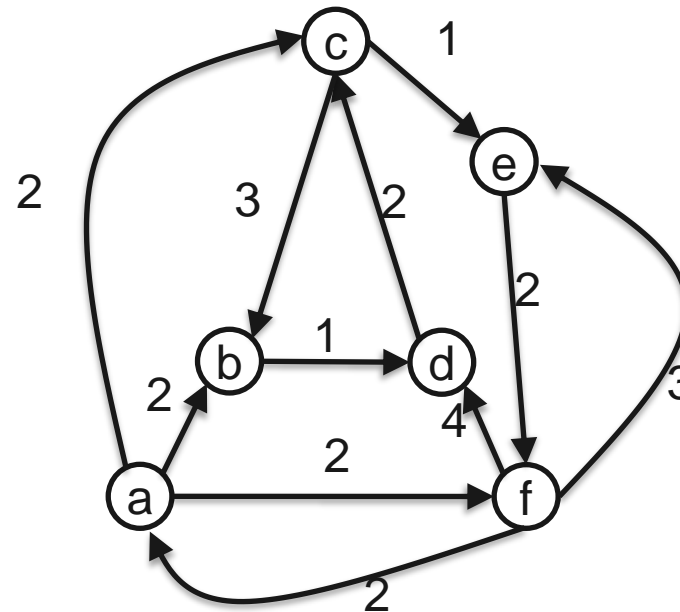
- Notation:
  - $\omega: E \rightarrow \mathbb{N}$ , for  $X \subseteq E$ ,  $\omega(X) = \sum_{e \in X} \omega(e)$ .
  - Path  $P$ : sequence of distinct consecutively adjacent vertices.
  - $V[P], E[P]$  are used vertices and edges
  - TSP: given  $G = (V, E)$ ,  $\omega: E \rightarrow \mathbb{N}$ . Let  $s \in V$ .
  - Find path  $P$  from  $s$  to  $t$  with  $V[P] = V$  minimizing  $\omega(E[P]) + \omega(t, s)$



# Traveling Salesman Problem

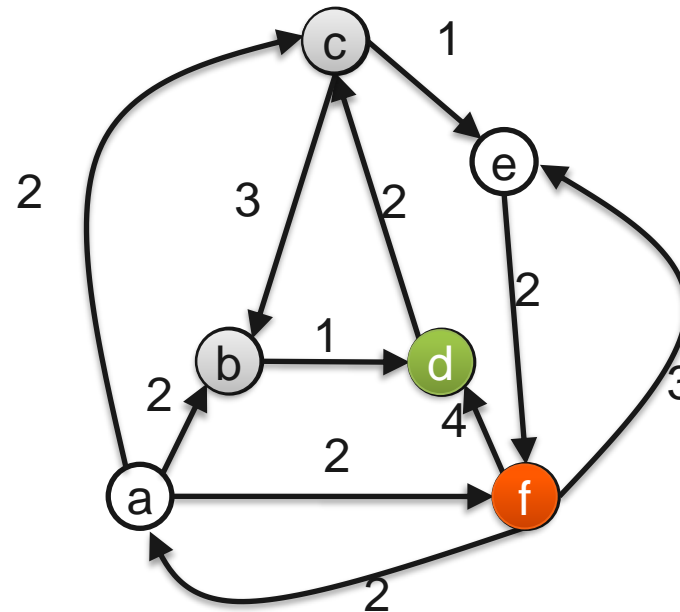
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- $P=(a,b,d,c)$ 
  - is a path from  $a$  to  $c$
  - $V[P]=\{a,b,d,c\}$
  - $E[P] =\{ab,bd,dc\}$
  - $\omega(P) = 2+1+2 = 5$



# Traveling Salesman Problem

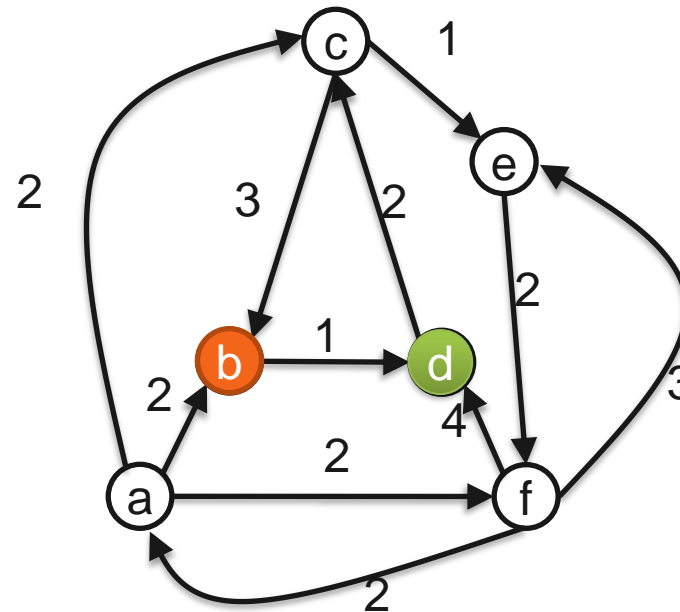
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- $s=d$ 
  - only  $b, f$  are candidates for  $t$



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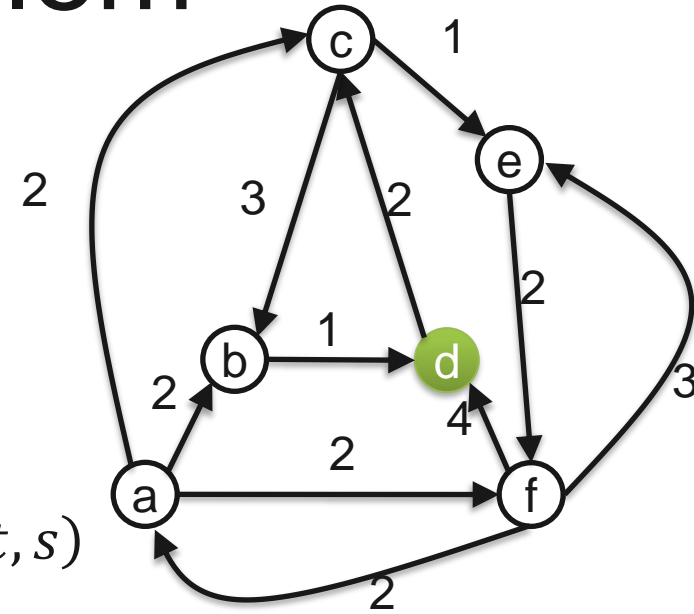
- $s=d$ 
  - only  $b, f$  are candidates for  $t$
  - $P=(d, c, e, f, a, b)$ ;  $\omega(P) = 9$
  - $\omega(E[P]) + \omega(t, s) = 10$



# Traveling Salesman Problem

- Notation:

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- $A_t[X] = \min\{\omega(E[P]): P \text{ path from } s \text{ to } t, \text{ and } V[P] \setminus s = X\}$ 
  - Only defined for  $t \in X, X \subseteq V \setminus s$
  - $A_b[\{c, b\}] = 5$
  - $A_a[\{c, e, f, a\}] = 7$

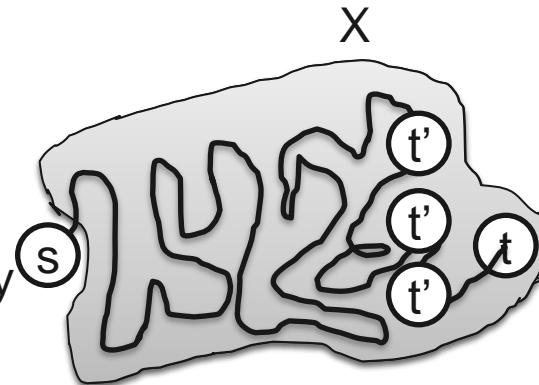


# Traveling Salesman Problem

- $A_t[X] = \min\{\omega(E[P]): P \text{ path from } s \text{ to } t, \text{ and } V[P] \setminus s = X\}$

$$A_t[X] = \begin{cases} \infty, & \text{if } |X| = 1 \text{ and } (s, t) \notin E, \\ \omega(s, t), & \text{if } |X| = 1 \text{ and } (s, t) \in E, \\ \min_{t' \in N^-(t) \cap X} A_{t'}[X \setminus t] + \omega(t', t), & \text{otherwise.} \end{cases}$$

- If  $|X| = 1$ , only allowed path is  $(s, t)$
- If  $|X| > 1$ :
- To formally argue the equality:
  - Inequalities in both direction:
    - LHS  $\geq$  RHS: every path is built in this way
    - LHS  $\leq$  RHS: adding edge  $t', t$  to path obtained from  $A_{t'}[X \setminus t]$  gives new path.



# Traveling Salesman Problem

- $A_t[X] = \min\{\omega(E[P]): P \text{ path from } s \text{ to } t, \text{ and } V[P] \setminus s = X\}$

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**Algorithm** tsp( $G = (V, E), \omega$ )

**Output:** The minimum  $\omega(E[C])$  over all cycles of  $G$  (e.g., cycles  $C$  satisfying  $V[C] = V$ ).

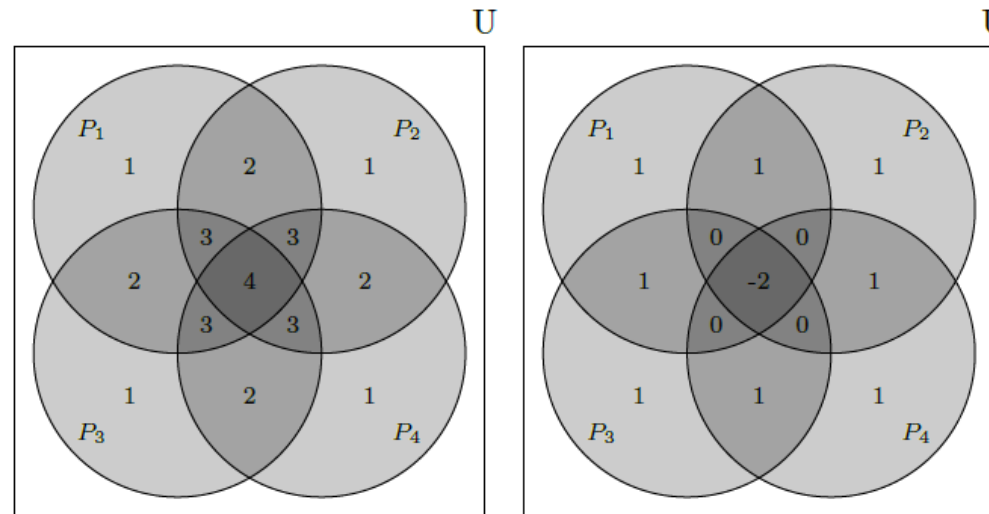
- 1: Pick an arbitrary vertex  $s \in V$
- 2: Initiate a table  $A_t[X]$  for every  $X \subseteq V \setminus s$  and  $t \in X$ .
- 3: Set  $A_t[\{t\}] = \omega(s, t)$  for every  $t \in V$ , where  $\omega(s, t) = \infty$  if  $(s, t) \notin E$ .
- 4: **for**  $i = 2$  to  $n$  **do**
- 5:     **for**  $t \in V \setminus s$  and  $X \subseteq V \setminus s$  such that  $|X| = i$  and  $t \in X$  **do**
- 6:         Set  $A_t[X] = \min_{t' \in N^-(t) \cap X} A_{t'}[X \setminus t] + \omega(t', t)$ .
- 7: **return**  $\min_{t \in N^-(V)} A_t[X] + \omega(t, s)$ .

- Gives  $O^*(2^n)$  time.

# Inclusion Exclusion

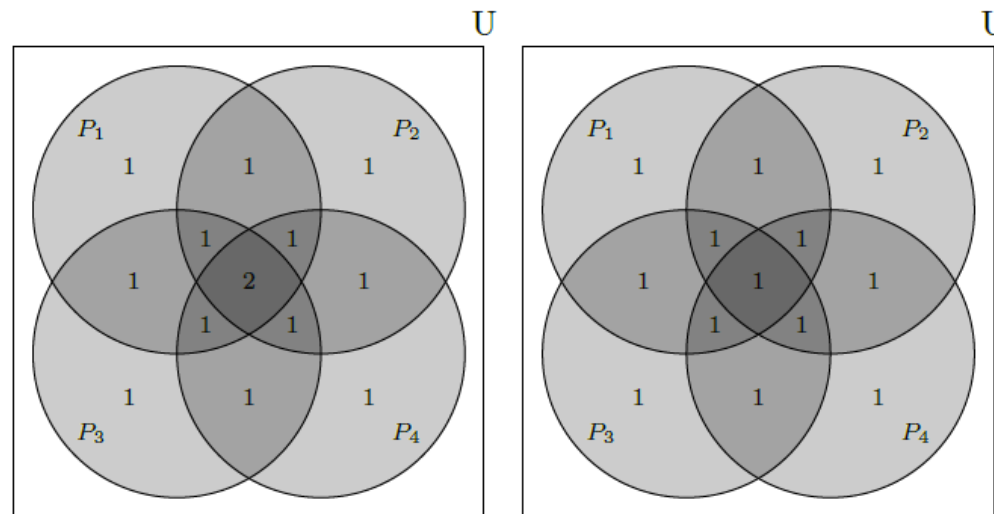
- Classical version: express the size of a union as size of an intersection: if  $P_1, P_2 \subseteq U$ 
$$|P_1 \cup P_2| = |P_1| + |P_2| - |P_1 \cap P_2|$$
- We are often interested in intersections:
$$|P_1 \cap P_2| = |U| - |\overline{P_1}| - |\overline{P_2}| + |\overline{P_1 \cap P_2}|$$
- Generalizes to  $n$  sets.

# Computing $|P_1 \cup P_2 \cup P_3 \cup P_4|$



(a)  $\sum_i |P_i|$

(b)  $-\sum_{i < j} |P_i \cap P_j|$



(c)  $+\sum_{i < j < k} |P_i \cap P_j \cap P_k|$

(d)  $-\sum_{i < j < k < l} |P_i \cap P_j \cap P_k \cap P_l|$

# Inclusion Exclusion Formula

- If  $P_1, \dots, P_n \subseteq U, \bar{P}_i = U \setminus P_i, \bigcap_{i \in \emptyset} \bar{P}_i = U,$

$$\left| \bigcap_{i=1}^n P_i \right| = \sum_{F \subseteq \{1, \dots, n\}} (-1)^{|F|} \left| \bigcap_{i \in F} \bar{P}_i \right|.$$

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- Proof: for  $e \in U,$  let  $p(e) = \{i: e \in P_i\}$

$$\begin{aligned} \sum_{F \subseteq \{1, \dots, n\}} (-1)^{|F|} \left| \bigcap_{i \in F} \bar{P}_i \right| &= \sum_{F \subseteq \{1, \dots, n\}} (-1)^{|F|} |\{e \in U : p(e) \cap F = \emptyset\}| \\ &= \sum_{e \in U} \sum_{F \subseteq \{1, \dots, n\} \setminus p(e)} (-1)^{|F|}. \end{aligned}$$

- $\sum_{Y \subseteq X} (-1)^{|Y|}$  is 1 if  $X = \emptyset$  and 0 otherwise by bin thm

$$\sum_{y \subseteq X} (-1)^{|Y|} = \sum_{i=0}^{|X|} \binom{|X|}{i} (-1)^i = (1 - 1)^{|X|}$$

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- $\sum_{Y \subseteq X} (-1)^{|Y|}$  is 1 if  $X = \emptyset$  and 0 otherwise by bin thm (or: every non empty set has equally even as odd subsets)

# k-coloring in $O^*(2^n)$ time

- Equivalently: can we cover the vertices with  $k$  independent sets?
- Let  $U = \{(I_1, \dots, I_k): I_i \text{ ind. set of } G\}$
- Let  $P_v = \{(I_1, \dots, I_k) \in U: v \in I_i, \text{ for some } i\}$
- $|\bigcap_{v \in V} P_v| = \# \text{coverings with } k \text{ ind. sets}$

$$|\bigcap_{i=1}^n P_i| = \sum_{F \subseteq \{1, \dots, n\}} (-1)^{|F|} |\bigcap_{i \in F} \overline{P}_i|.$$

$|\bigcap_{i \in F} \overline{P}_i| = \# \text{ind. Sets in } G[V \setminus F] \text{ to the power } k.$



## k-coloring in $O^*(2^n)$ time

- For  $X \subseteq G$ , let  $i[X] = \#ind. sets in G[X]$
- Use DP to compute  $i[X]$  for every  $X \subseteq V$

$$i[X] = \begin{cases} 1 & X = \emptyset \\ i[X \setminus v] + i[X \setminus N[v]] & \text{if } v \in X. \end{cases}$$

- Given this table we can evaluate the formula

$$\sum_{F \subseteq V} (-1)^{|F|} i[V \setminus F]^k$$

- In time  $O^*(2^n)$ .

# Hamiltonian Cycle in $O^*(2^n)$ time and polynomial space

- Notation:
  - *Walk*: sequence  $P$  of vertices  $p_1, \dots, p_l$  s.t  $(p_i, p_{i+1}) \in E$
  - *Length* of  $P = l - 1$  (# of edges)
  - *From  $s$  to  $t$* :  $p_1 = s, p_l = t$ , *cyclic* if  $p_1 = p_l$
- HC: cyclic walk of length  $n$  visiting all vertices.

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- $U =$  all cyclic walks of length  $n$  in  $G$
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$$|\bigcap_{i=1}^n P_i| = \sum_{F \subseteq \{1, \dots, n\}} (-1)^{|F|} |\bigcap_{i \in F} \overline{P}_i|.$$

$|\bigcap_{i \in F} \overline{P}_i|$  equals #cyclic walks of length  $n$  in  $G[V \setminus F]$

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- *From  $s$  to  $t$* :  $p_1 = s, p_l = t$ , *cyclic* if  $p_1 = p_l$

- $w_F(s, t, k)$  = #length  $k$  walks from  $s$  to  $t$  avoiding  $F$

$$w_F(s, t, k) = \begin{cases} 0 & \text{if } k = 0 \text{ and } s \neq t \\ 1 & \text{if } k = 0 \text{ and } s = t, \\ \sum_{t' \in N^-(t) \setminus F} w_F(s, t', k - 1) & \text{otherwise.} \end{cases}$$

- #cyclic walks of length  $n$  avoiding  $F$  can be computed as  $\sum_{s \in V \setminus F} w_F(s, s, n)$